# *hypre* Reference Manual

— Version 1.8.2b —

# Contents

1

# extern Struct System Interface

**Names**



This interface represents a structured-grid conceptual view of a linear system.


**Author:** Robert D. Falgout


1.1

## Struct Grids

**Names**

typedef struct hypre_StructGrid_struct* **HYPRE_StructGrid**

*A grid object is constructed out of several "boxes", defined on a global abstract index space*

int

**HYPRE_StructGridCreate** (MPI_Comm comm, int ndim, HYPRE_StructGrid *grid)

*Create an* `ndim`*-dimensional grid object*

1.1.1 int

**HYPRE_StructGridDestroy** (HYPRE_StructGrid grid)

*Destroy a grid object* ..... 5

int

**HYPRE_StructGridSetExtents** (HYPRE_StructGrid grid, int *ilower, int *iupper)

*Set the extents for a box on the grid*

int

**HYPRE_StructGridAssemble** (HYPRE_StructGrid grid)
*Finalize the construction of the grid before using*

int
**HYPRE_StructGridSetPeriodic** (HYPRE_StructGrid grid, int *periodic)
*(Optional) Set periodic*

int
**HYPRE_StructGridSetNumGhost** (HYPRE_StructGrid grid,
int *num_ghost)
*(Optional) Set the ghost layer in the grid object*

### 1.1.1

int **HYPRE_StructGridDestroy** (HYPRE_StructGrid grid)

Destroy a grid object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

## 1.2

## Struct Stencils

**Names**

typedef struct hypre_StructStencil_struct* **HYPRE_StructStencil**
*The stencil object*

int
**HYPRE_StructStencilCreate** (int ndim, int size,
HYPRE_StructStencil *stencil)
*Create a stencil object for the specified number of spatial dimensions and stencil entries*

int
**HYPRE_StructStencilDestroy** (HYPRE_StructStencil stencil)
*Destroy a stencil object*

1.2.1 int
**HYPRE_StructStencilSetElement** (HYPRE_StructStencil stencil, int entry,
int *offset)
*Set a stencil entry* ..... 6

1.2.1

int
**HYPRE_StructStencilSetElement** (HYPRE_StructStencil stencil, int entry, int *offset)

Set a stencil entry.

NOTE: The name of this routine will eventually be changed to `HYPRE_StructStencilSetEntry`.

1.3

## Struct Matrices

**Names**

typedef struct hypre_StructMatrix_struct* **HYPRE_StructMatrix**
*The matrix object*

int
**HYPRE_StructMatrixCreate** (MPI_Comm comm, HYPRE_StructGrid grid,
HYPRE_StructStencil stencil,
HYPRE_StructMatrix *matrix)
*Create a matrix object*

int
**HYPRE_StructMatrixDestroy** (HYPRE_StructMatrix matrix)
*Destroy a matrix object*

int
**HYPRE_StructMatrixInitialize** (HYPRE_StructMatrix matrix)
*Prepare a matrix object for setting coefficient values*

int
**HYPRE_StructMatrixSetValues** (HYPRE_StructMatrix matrix, int *index,
int nentries, int *entries, double *values)
*Set matrix coefficients index by index*

int
**HYPRE_StructMatrixSetBoxValues** (HYPRE_StructMatrix matrix,
int *ilower, int *iupper, int nentries,
int *entries, double *values)
*Set matrix coefficients a box at a time*

int

**1.3.1**

int
**HYPRE_StructMatrixSetSymmetric** (HYPRE_StructMatrix matrix, int symmetric)

(Optional) Define symmetry properties of the matrix. By default, matrices are assumed to be nonsymmetric. Significant storage savings can be made if the matrix is symmetric.

**1.3.2**

int
**HYPRE_StructMatrixPrint** (const char *filename, HYPRE_StructMatrix matrix, int all)

Print the matrix to file. This is mainly for debugging purposes.

## Struct Vectors

**Names**

typedef struct hypre_StructVector_struct* **HYPRE_StructVector**
*The vector object*

int
**HYPRE_StructVectorCreate** (MPI_Comm comm, HYPRE_StructGrid grid,
HYPRE_StructVector *vector)
*Create a vector object*

int
**HYPRE_StructVectorDestroy** (HYPRE_StructVector vector)
*Destroy a vector object*

int
**HYPRE_StructVectorInitialize** (HYPRE_StructVector vector)
*Prepare a vector object for setting coefficient values*

int
**HYPRE_StructVectorSetValues** (HYPRE_StructVector vector, int *index,
double value)
*Set vector coefficients index by index*

int
**HYPRE_StructVectorSetBoxValues** (HYPRE_StructVector vector,
int *ilower, int *iupper,
double *values)
*Set vector coefficients a box at a time*

int
**HYPRE_StructVectorAddToValues** (HYPRE_StructVector vector,
int *index, double value)
*Set vector coefficients index by index*

int
**HYPRE_StructVectorAddToBoxValues** (HYPRE_StructVector vector,
int *ilower, int *iupper,
double *values)
*Set vector coefficients a box at a time*

int
**HYPRE_StructVectorAssemble** (HYPRE_StructVector vector)
*Finalize the construction of the vector before using*

int
**HYPRE_StructVectorGetValues** (HYPRE_StructVector vector, int *index,
double *value)
*Get vector coefficients index by index*

int

**1.4.1**

int
**HYPRE_StructVectorPrint** (const char *filename, HYPRE_StructVector vector, int all)

Print the vector to file. This is mainly for debugging purposes.

2

# extern SStruct System Interface

**Names**



This interface represents a semi-structured-grid conceptual view of a linear system.

**Author:** Robert D. Falgout

2.1

## SStruct Grids

**Names**

**HYPRE_SStructGridSetExtents** (HYPRE_SStructGrid grid, int part,
int *ilower, int *iupper)

*Set the extents for a box on a structured part of the grid*

int
**HYPRE_SStructGridSetVariables** (HYPRE_SStructGrid grid, int part,
int nvars,
HYPRE_SStructVariable *vartypes)

*Describe the variables that live on a structured part of the grid*

2.1.4 int
**HYPRE_SStructGridAddVariables** (HYPRE_SStructGrid grid, int part,
int *index, int nvars,
HYPRE_SStructVariable *vartypes)

*Describe additional variables that live at a particular index* ..... 13

2.1.5 int
**HYPRE_SStructGridSetNeighborBox** (HYPRE_SStructGrid grid, int part,
int *ilower, int *iupper,
int nbor_part, int *nbor_ilower,
int *nbor_iupper, int *index_map)

*Describe how regions just outside of a part relate to other parts* ..... 13

2.1.6 int
**HYPRE_SStructGridAddUnstructuredPart** (HYPRE_SStructGrid grid,
int ilower, int iupper)

*Add an unstructured part to the grid* ..... 14

int
**HYPRE_SStructGridAssemble** (HYPRE_SStructGrid grid)

*Finalize the construction of the grid before using*

int
**HYPRE_SStructGridSetPeriodic** (HYPRE_SStructGrid grid, int part,
int *periodic)

*(Optional) Set periodic for a particular part*

int
**HYPRE_SStructGridSetNumGhost** (HYPRE_SStructGrid grid,
int *num_ghost)

*Setting ghost in the sgrids*

**2.1.1**

## #define **HYPRE_SStructGrid**

A grid object is constructed out of several structured "parts" and an optional unstructured "part". Each structured part has its own abstract index space.

2.1.2

## #define **HYPRE_SStructVariable**

An enumerated type that supports cell centered, node centered, face centered, and edge centered variables. Face centered variables are split into x-face, y-face, and z-face variables, and edge centered variables are split into x-edge, y-edge, and z-edge variables. The edge centered variable types are only used in 3D. In 2D, edge centered variables are handled by the face centered types.

Variables are referenced relative to an abstract (cell centered) index in the following way:

- cell centered variables are aligned with the index;
- node centered variables are aligned with the cell corner at relative index (1/2, 1/2, 1/2);
- x-face, y-face, and z-face centered variables are aligned with the faces at relative indexes (1/2, 0, 0), (0, 1/2, 0), and (0, 0, 1/2), respectively;
- x-edge, y-edge, and z-edge centered variables are aligned with the edges at relative indexes (0, 1/2, 1/2), (1/2, 0, 1/2), and (1/2, 1/2, 0), respectively.

The supported identifiers are:

- `HYPRE_SSTRUCT_VARIABLE_CELL`
- `HYPRE_SSTRUCT_VARIABLE_NODE`
- `HYPRE_SSTRUCT_VARIABLE_XFACE`
- `HYPRE_SSTRUCT_VARIABLE_YFACE`
- `HYPRE_SSTRUCT_VARIABLE_ZFACE`
- `HYPRE_SSTRUCT_VARIABLE_XEDGE`
- `HYPRE_SSTRUCT_VARIABLE_YEDGE`
- `HYPRE_SSTRUCT_VARIABLE_ZEDGE`

NOTE: Although variables are referenced relative to a unique abstract cell-centered index, some variables are associated with multiple grid cells. For example, node centered variables in 3D are associated with 8 cells (away from boundaries). Although grid cells are distributed uniquely to different processes, variables may be owned by multiple processes because they may be associated with multiple cells.

**2.1.3**

int **HYPRE_SStructGridDestroy** (HYPRE_SStructGrid grid)

Destroy a grid object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**2.1.4**

int
**HYPRE_SStructGridAddVariables** (HYPRE_SStructGrid grid, int part, int *index, int nvars, HYPRE_SStructVariable *vartypes)

Describe additional variables that live at a particular index. These variables are appended to the array of variables set in HYPRE_SStructGridSetVariables (→ *page 11*), and are referenced as such.

**2.1.5**

int
**HYPRE_SStructGridSetNeighborBox** (HYPRE_SStructGrid grid, int part, int *ilower, int *iupper, int nbor_part, int *nbor_ilower, int *nbor_iupper, int *index_map)

Describe how regions just outside of a part relate to other parts. This is done a box at a time.

The indexes `ilower` and `iupper` map directly to the indexes `nbor_ilower` and `nbor_iupper`. Although, it is required that indexes increase from `ilower` to `iupper`, indexes may increase and/or decrease from `nbor_ilower` to `nbor_iupper`.

The `index_map` describes the mapping of indexes 0, 1, and 2 on part `part` to the corresponding indexes on part `nbor_part`. For example, triple (1, 2, 0) means that indexes 0, 1, and 2 on part `part` map to indexes 1, 2, and 0 on part `nbor_part`, respectively.

NOTE: All parts related to each other via this routine must have an identical list of variables and variable types. For example, if part 0 has only two variables on it, a cell centered variable and a node centered variable, and we declare part 1 to be a neighbor of part 0, then part 1 must also have only two variables on it, and they must be of type cell and node.

### 2.1.6

int
**HYPRE_SStructGridAddUnstructuredPart** (HYPRE_SStructGrid grid, int ilower, int iupper)

Add an unstructured part to the grid. The variables in the unstructured part of the grid are referenced by a global rank between 0 and the total number of unstructured variables minus one. Each process owns some unique consecutive range of variables, defined by `ilower` and `iupper`.

NOTE: This is just a placeholder. This part of the interface is not finished.

## 2.2

## SStruct Stencils

**Names**

typedef struct hypre_SStructStencil_struct* **HYPRE_SStructStencil**
*The stencil object*

int
**HYPRE_SStructStencilCreate** (int ndim, int size,
HYPRE_SStructStencil *stencil)
*Create a stencil object for the specified number of spatial dimensions and stencil entries*

int
**HYPRE_SStructStencilDestroy** (HYPRE_SStructStencil stencil)
*Destroy a stencil object*

int
**HYPRE_SStructStencilSetEntry** (HYPRE_SStructStencil stencil, int entry,
int *offset, int var)
*Set a stencil entry*

2.3

## SStruct Graphs

**Names**

typedef struct hypre_SStructGraph_struct* **HYPRE_SStructGraph**

*The graph object is used to describe the nonzero structure of a matrix*

int
**HYPRE_SStructGraphCreate** (MPI_Comm comm,
HYPRE_SStructGrid grid,
HYPRE_SStructGraph *graph)

*Create a graph object*

int
**HYPRE_SStructGraphDestroy** (HYPRE_SStructGraph graph)

*Destroy a graph object*

int
**HYPRE_SStructGraphSetStencil** (HYPRE_SStructGraph graph, int part,
int var, HYPRE_SStructStencil stencil)

*Set the stencil for a variable on a structured part of the grid*



int
**HYPRE_SStructGraphAssemble** (HYPRE_SStructGraph graph)

*Finalize the construction of the graph before using*

2.3.1

### int **HYPRE_SStructGraphAddEntries** (HYPRE_SStructGraph graph, int part, int *index, int var, int to_part, int *to_index, int to_var)

Add a non-stencil graph entry at a particular index. This graph entry is appended to the existing graph entries, and is referenced as such.

NOTE: Users are required to set graph entries on all processes that own the associated variables. This means that some data will be multiply defined.

**2.3.2**

int
**HYPRE_SStructGraphSetObjectType** (HYPRE_SStructGraph graph, int type)

It is used before AddEntries and Assemble to compute the right ranks in the graph. Currently, `type` can be either `HYPRE_SSTRUCT` (the default) or `HYPRE_PARCSR`.

**2.4**

## SStruct Matrices

**Names**

typedef struct hypre_SStructMatrix_struct* **HYPRE_SStructMatrix**
*The matrix object*

int
**HYPRE_SStructMatrixCreate** (MPI_Comm comm,
HYPRE_SStructGraph graph,
HYPRE_SStructMatrix *matrix)
*Create a matrix object*

int
**HYPRE_SStructMatrixDestroy** (HYPRE_SStructMatrix matrix)
*Destroy a matrix object*

int
**HYPRE_SStructMatrixInitialize** (HYPRE_SStructMatrix matrix)
*Prepare a matrix object for setting coefficient values*

2.4.1 int
**HYPRE_SStructMatrixSetValues** (HYPRE_SStructMatrix matrix, int part,
int *index, int var, int nentries,
int *entries, double *values)
*Set matrix coefficients index by index* ..... 18

2.4.2 int

**2.4.1**

int
**HYPRE_SStructMatrixSetValues** (HYPRE_SStructMatrix matrix, int part, int *index, int var, int nentries, int *entries, double *values)

Set matrix coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type (there are no such restrictions for non-stencil entries).

If the matrix is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructMatrixSetComplex (→ *page 17*)

**2.4.2**

int
**HYPRE_SStructMatrixSetBoxValues** (HYPRE_SStructMatrix matrix, int part, int *ilower, int *iupper, int var, int nentries, int *entries, double *values)

Set matrix coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type (there are no such restrictions for non-stencil entries).

If the matrix is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructMatrixSetComplex (→ *page 17*)

**2.4.3**

int
**HYPRE_SStructMatrixAddToValues** (HYPRE_SStructMatrix matrix, int part, int *index, int var, int nentries, int *entries, double *values)

Add to matrix coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type.

If the matrix is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructMatrixSetComplex (→ *page 17*)

**2.4.4**

int
**HYPRE_SStructMatrixAddToBoxValues** (HYPRE_SStructMatrix matrix, int part, int *ilower, int *iupper, int var, int nentries, int *entries, double *values)

Add to matrix coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of stencil type. Also, they must all represent couplings to the same variable type.

If the matrix is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructMatrixSetComplex (→ *page 17*)

**2.4.5**

int
**HYPRE_SStructMatrixSetSymmetric** (HYPRE_SStructMatrix matrix, int part, int var, int to_var, int symmetric)

Define symmetry properties for the stencil entries in the matrix. The boolean argument `symmetric` is applied to stencil entries on part `part` that couple variable `var` to variable `to_var`. A value of -1 may be used for `part`, `var`, or `to_var` to specify "all". For example, if `part` and `to_var` are set to -1, then the boolean is applied to stencil entries on all parts that couple variable `var` to all other variables.

By default, matrices are assumed to be nonsymmetric. Significant storage savings can be made if the matrix is symmetric.

**2.4.6**

int
**HYPRE_SStructMatrixSetObjectType** (HYPRE_SStructMatrix matrix, int type)

Set the storage type of the matrix object to be constructed. Currently, `type` can be either `HYPRE_SSTRUCT` (the default) or `HYPRE_PARCSR`.

**See Also:** HYPRE_SStructMatrixGetObject (→2.4.7, *page 20*)

**2.4.7**

int
**HYPRE_SStructMatrixGetObject** (HYPRE_SStructMatrix matrix, void **object)

Get a reference to the constructed matrix object.

**See Also:** HYPRE_SStructMatrixSetObjectType (→2.4.6, *page 20*)

**2.4.8**

int
**HYPRE_SStructMatrixPrint** (const char *filename, HYPRE_SStructMatrix matrix, int all)

Print the matrix to file. This is mainly for debugging purposes.

**2.5**

## SStruct Vectors

**Names**

typedef struct hypre_SStructVector_struct* **HYPRE_SStructVector**
*The vector object*

int
**HYPRE_SStructVectorCreate** (MPI_Comm comm,
HYPRE_SStructGrid grid,
HYPRE_SStructVector *vector)
*Create a vector object*

int
**HYPRE_SStructVectorDestroy** (HYPRE_SStructVector vector)
*Destroy a vector object*

int
**HYPRE_SStructVectorInitialize** (HYPRE_SStructVector vector)
*Prepare a vector object for setting coefficient values*

2.5.1 int
**HYPRE_SStructVectorSetValues** (HYPRE_SStructVector vector, int part,
int *index, int var, double *value)
*Set vector coefficients index by index* ..... 22

2.5.2 int
**HYPRE_SStructVectorSetBoxValues** (HYPRE_SStructVector vector,
int part, int *ilower, int *iupper,
int var, double *values)
*Set vector coefficients a box at a time* ..... 23

2.5.3 int
**HYPRE_SStructVectorAddToValues** (HYPRE_SStructVector vector,
int part, int *index, int var,
double *value)
*Set vector coefficients index by index* ..... 23

2.5.4 int

**2.5.1**

int
**HYPRE_SStructVectorSetValues** (HYPRE_SStructVector vector, int part, int *index, int var, double *value)

Set vector coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then `value` consists of a pair of doubles representing the real and imaginary parts of the complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.2**

int
**HYPRE_SStructVectorSetBoxValues** (HYPRE_SStructVector vector, int part, int *ilower, int *iupper, int var, double *values)

Set vector coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.3**

int
**HYPRE_SStructVectorAddToValues** (HYPRE_SStructVector vector, int part, int *index, int var, double *value)

Set vector coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then `value` consists of a pair of doubles representing the real and imaginary parts of the complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.4**

int
**HYPRE_SStructVectorAddToBoxValues** (HYPRE_SStructVector vector, int part, int *ilower, int *iupper, int var, double *values)

Set vector coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.5**

int
**HYPRE_SStructVectorGetValues** (HYPRE_SStructVector vector, int part, int *index, int var, double *value)

Get vector coefficients index by index.

NOTE: Users may only get values on processes that own the associated variables.

If the vector is complex, then `value` consists of a pair of doubles representing the real and imaginary parts of the complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.6**

int
**HYPRE_SStructVectorGetBoxValues** (HYPRE_SStructVector vector, int part, int *ilower, int *iupper, int var, double *values)

Get vector coefficients a box at a time.

NOTE: Users may only get values on processes that own the associated variables.

If the vector is complex, then `values` consists of pairs of doubles representing the real and imaginary parts of each complex value.

**See Also:** HYPRE_SStructVectorSetComplex (→ *page 22*)

**2.5.7**

int
**HYPRE_SStructVectorSetObjectType** (HYPRE_SStructVector vector, int type)

Set the storage type of the vector object to be constructed. Currently, `type` can be either `HYPRE_SSTRUCT` (the default) or `HYPRE_PARCSR`.

**See Also:** HYPRE_SStructVectorGetObject (→2.5.8, *page 25*)

**2.5.8**

int
**HYPRE_SStructVectorGetObject** (HYPRE_SStructVector vector, void **object)

Get a reference to the constructed vector object.

**See Also:** HYPRE_SStructVectorSetObjectType (→2.5.7, *page 25*)

**2.5.9**

int
**HYPRE_SStructVectorPrint** (const char *filename, HYPRE_SStructVector vector, int all)

Print the vector to file. This is mainly for debugging purposes.

3

# extern **IJ System Interface**

**Names**



This interface represents a linear-algebraic conceptual view of a linear system. The 'I' and 'J' in the name are meant to be mnemonic for the traditional matrix notation A(I,J).

3.1

## IJ Matrices

**Names**

### 3.1.1

int
**HYPRE_IJMatrixCreate** (MPI_Comm comm, int ilower, int iupper, int jlower, int jupper, HYPRE_IJMatrix *matrix)

Create a matrix object. Each process owns some unique consecutive range of rows, indicated by the global row indices `ilower` and `iupper`. The row data is required to be such that the value of `ilower` on any process $p$ be exactly one more than the value of `iupper` on process $p-1$. Note that the first row of the global matrix may start with any integer value. In particular, one may use zero- or one-based indexing.

For square matrices, `jlower` and `jupper` typically should match `ilower` and `iupper`, respectively. For rectangular matrices, `jlower` and `jupper` should define a partitioning of the columns. This partitioning must be used for any vector $v$ that will be used in matrix-vector products with the rectangular matrix. The matrix data structure may use `jlower` and `jupper` to store the diagonal blocks (rectangular in general) of the matrix separately from the rest of the matrix.

Collective.

### 3.1.2

int **HYPRE_IJMatrixDestroy** (HYPRE_IJMatrix matrix)

Destroy a matrix object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

### 3.1.3

int **HYPRE_IJMatrixInitialize** (HYPRE_IJMatrix matrix)

Prepare a matrix object for setting coefficient values. This routine will also re-initialize an already assembled matrix, allowing users to modify coefficient values.

**3.1.4**

int
**HYPRE_IJMatrixSetValues** (HYPRE_IJMatrix matrix, int nrows, int *ncols, const int *rows, const int *cols, const double *values)

Sets values for `nrows` rows or partial rows of the matrix. The arrays `ncols` and `rows` are of dimension `nrows` and contain the number of columns in each row and the row indices, respectively. The array `cols` contains the column indices for each of the `rows`, and is ordered by rows. The data in the `values` array corresponds directly to the column entries in `cols`. Erases any previous values at the specified locations and replaces them with new ones, or, if there was no value there before, inserts a new one.

Not collective.

**3.1.5**

int
**HYPRE_IJMatrixAddToValues** (HYPRE_IJMatrix matrix, int nrows, int *ncols, const int *rows, const int *cols, const double *values)

Adds to values for `nrows` rows or partial rows of the matrix. Usage details are analogous to HYPRE_IJMatrixSetValues (→3.1.4, *page 30*). Adds to any previous values at the specified locations, or, if there was no value there before, inserts a new one.

Not collective.

**3.1.6**

int
**HYPRE_IJMatrixGetValues** (HYPRE_IJMatrix matrix, int nrows, int *ncols, int *rows, int *cols, double *values)

Gets values for `nrows` rows or partial rows of the matrix. Usage details are analogous to HYPRE_IJMatrixSetValues (→3.1.4, *page 30*).

**3.1.7**

int **HYPRE_IJMatrixSetObjectType** (HYPRE_IJMatrix matrix, int type)

Set the storage type of the matrix object to be constructed. Currently, `type` can only be `HYPRE_PARCSR`.

Not collective, but must be the same on all processes.

**See Also:** HYPRE_IJMatrixGetObject (→3.1.8, *page 31*)

**3.1.8**

int **HYPRE_IJMatrixGetObject** (HYPRE_IJMatrix matrix, void **object)

Get a reference to the constructed matrix object.

**See Also:** HYPRE_IJMatrixSetObjectType (→3.1.7, *page 31*)

**3.1.9**

int **HYPRE_IJMatrixSetRowSizes** (HYPRE_IJMatrix matrix, const int *sizes)

(Optional) Set the max number of nonzeros to expect in each row. The array `sizes` contains estimated sizes for each row on this process. This call can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

### 3.1.10

int
**HYPRE_IJMatrixSetDiagOffdSizes** (HYPRE_IJMatrix matrix, const int *diag_sizes, const int *offdiag_sizes)

(Optional) Set the max number of nonzeros to expect in each row of the diagonal and off-diagonal blocks. The diagonal block is the submatrix whose column numbers correspond to rows owned by this process, and the off-diagonal block is everything else. The arrays `diag_sizes` and `offdiag_sizes` contain estimated sizes for each row of the diagonal and off-diagonal blocks, respectively. This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

### 3.1.11

int
**HYPRE_IJMatrixRead** (const char *filename, MPI_Comm comm, int type, HYPRE_IJMatrix *matrix)

Read the matrix from file. This is mainly for debugging purposes.

### 3.1.12

int **HYPRE_IJMatrixPrint** (HYPRE_IJMatrix matrix, const char *filename)

Print the matrix to file. This is mainly for debugging purposes.

## 3.2

## IJ Vectors

**Names**

typedef struct hypre_IJVector_struct* **HYPRE_IJVector**
*The vector object*

3.2.1 int
**HYPRE_IJVectorCreate** (MPI_Comm comm, int jlower, int jupper, HYPRE_IJVector *vector)
*Create a vector object* ..... 34

3.2.2 int
**HYPRE_IJVectorDestroy** (HYPRE_IJVector vector)
*Destroy a vector object* ..... 34

3.2.3 int
**HYPRE_IJVectorInitialize** (HYPRE_IJVector vector)
*Prepare a vector object for setting coefficient values* ..... 34

3.2.4 int
**HYPRE_IJVectorSetValues** (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)
*Sets values in vector* ..... 35

3.2.5 int
**HYPRE_IJVectorAddToValues** (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)
*Adds to values in vector* ..... 35

int
**HYPRE_IJVectorAssemble** (HYPRE_IJVector vector)
*Finalize the construction of the vector before using*

3.2.6 int
**HYPRE_IJVectorGetValues** (HYPRE_IJVector vector, int nvalues, const int *indices, double *values)
*Gets values in vector* ..... 35

3.2.7 int
**HYPRE_IJVectorSetObjectType** (HYPRE_IJVector vector, int type)
*Set the storage type of the vector object to be constructed* ..... 36

int
**HYPRE_IJVectorGetObjectType** (HYPRE_IJVector vector, int *type)
*Get the storage type of the constructed vector object*

int
**HYPRE_IJVectorGetLocalRange** (HYPRE_IJVector vector, int *jlower, int *jupper)
*Returns range of the part of the vector owned by this processor*

3.2.8 int
**HYPRE_IJVectorGetObject** (HYPRE_IJVector vector, void **object)
*Get a reference to the constructed vector object* ..... 36

3.2.9 int
**HYPRE_IJVectorRead** (const char *filename, MPI_Comm comm, int type, HYPRE_IJVector *vector)
*Read the vector from file* ..... 36

3.2.10 int
**HYPRE_IJVectorPrint** (HYPRE_IJVector vector, const char *filename)
*Print the vector to file* ..... 36

**3.2.1**

int
**HYPRE_IJVectorCreate** (MPI_Comm comm, int jlower, int jupper, HYPRE_IJVector *vector)

Create a vector object. Each process owns some unique consecutive range of vector unknowns, indicated by the global indices `jlower` and `jupper`. The data is required to be such that the value of `jlower` on any process $p$ be exactly one more than the value of `jupper` on process $p-1$. Note that the first index of the global vector may start with any integer value. In particular, one may use zero- or one-based indexing.

Collective.

**3.2.2**

int **HYPRE_IJVectorDestroy** (HYPRE_IJVector vector)

Destroy a vector object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**3.2.3**

int **HYPRE_IJVectorInitialize** (HYPRE_IJVector vector)

Prepare a vector object for setting coefficient values. This routine will also re-initialize an already assembled vector, allowing users to modify coefficient values.

**3.2.4**

int
**HYPRE_IJVectorSetValues** (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)

Sets values in vector. The arrays `values` and `indices` are of dimension `nvalues` and contain the vector values to be set and the corresponding global vector indices, respectively. Erases any previous values at the specified locations and replaces them with new ones.

Not collective.

**3.2.5**

int
**HYPRE_IJVectorAddToValues** (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)

Adds to values in vector. Usage details are analogous to HYPRE_IJVectorSetValues (→3.2.4, *page 35*).

Not collective.

**3.2.6**

int
**HYPRE_IJVectorGetValues** (HYPRE_IJVector vector, int nvalues, const int *indices, double *values)

Gets values in vector. Usage details are analogous to HYPRE_IJVectorSetValues (→3.2.4, *page 35*).

Not collective.

**3.2.7**

int **HYPRE_IJVectorSetObjectType** (HYPRE_IJVector vector, int type)

Set the storage type of the vector object to be constructed. Currently, `type` can only be `HYPRE_PARCSR`.

Not collective, but must be the same on all processes.

**See Also:** HYPRE_IJVectorGetObject (→3.2.8, *page 36*)

**3.2.8**

int **HYPRE_IJVectorGetObject** (HYPRE_IJVector vector, void **object)

Get a reference to the constructed vector object.

**See Also:** HYPRE_IJVectorSetObjectType (→3.2.7, *page 36*)

**3.2.9**

int
**HYPRE_IJVectorRead** (const char *filename, MPI_Comm comm, int type, HYPRE_IJVector *vector)

Read the vector from file. This is mainly for debugging purposes.

**3.2.10**

int **HYPRE_IJVectorPrint** (HYPRE_IJVector vector, const char *filename)

Print the vector to file. This is mainly for debugging purposes.

4

# extern Struct Solvers

**Names**



These solvers use matrix/vector storage schemes that are tailored to structured grid problems.

4.1

## Struct Solvers

**Names**

typedef struct hypre_StructSolver_struct* **HYPRE_StructSolver**
*The solver object*

4.2

## Struct Jacobi Solver

int
**HYPRE_StructJacobiCreate** (MPI_Comm comm,
HYPRE_StructSolver *solver)

*Create a solver object*

4.2.1 int
**HYPRE_StructJacobiDestroy** (HYPRE_StructSolver solver)

*Destroy a solver object* ..... 39

int
**HYPRE_StructJacobiSetup** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x)

int
**HYPRE_StructJacobiSolve** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x)

*Solve the system*

int
**HYPRE_StructJacobiSetTol** (HYPRE_StructSolver solver, double tol)

*(Optional) Set the convergence tolerance*

int
**HYPRE_StructJacobiSetMaxIter** (HYPRE_StructSolver solver, int max_iter)

*(Optional) Set maximum number of iterations*

int
**HYPRE_StructJacobiSetZeroGuess** (HYPRE_StructSolver solver)

*(Optional) Use a zero initial guess*

int
**HYPRE_StructJacobiSetNonZeroGuess** (HYPRE_StructSolver solver)

*(Optional) Use a nonzero initial guess*

int
**HYPRE_StructJacobiGetNumIterations** (HYPRE_StructSolver solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_StructJacobiGetFinalRelativeResidualNorm**
(HYPRE_StructSolver
solver,
double *norm)

*Return the norm of the final relative residual*

**4.2.1**

int **HYPRE_StructJacobiDestroy** (HYPRE_StructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

## 4.3 Struct PFMG Solver

**Names**

int
**HYPRE_StructPFMGCreate** (MPI_Comm comm,
HYPRE_StructSolver *solver)

*Create a solver object*

int
**HYPRE_StructPFMGDestroy** (HYPRE_StructSolver solver)

*Destroy a solver object*

int
**HYPRE_StructPFMGSetup** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x)

int
**HYPRE_StructPFMGSolve** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x)

*Solve the system*

int
**HYPRE_StructPFMGSetTol** (HYPRE_StructSolver solver, double tol)

*(Optional) Set the convergence tolerance*

int
**HYPRE_StructPFMGSetMaxIter** (HYPRE_StructSolver solver,
int max_iter)

*(Optional) Set maximum number of iterations*

int
**HYPRE_StructPFMGSetRelChange** (HYPRE_StructSolver solver,
int rel_change)

*(Optional) Additionally require that the relative difference in successive iterates be small*

int

**HYPRE_StructPFMGSetZeroGuess** (HYPRE_StructSolver solver)

*(Optional) Use a zero initial guess*

int
**HYPRE_StructPFMGSetNonZeroGuess** (HYPRE_StructSolver solver)

*(Optional) Use a nonzero initial guess*

int
**HYPRE_StructPFMGSetRelaxType** (HYPRE_StructSolver solver,
int relax_type)

*(Optional) Set relaxation type*

int
**HYPRE_StructPFMGSetRAPType** (HYPRE_StructSolver solver,
int rap_type)

*(Optional) Set type of code used for coarse operator*

int
**HYPRE_StructPFMGSetNumPreRelax** (HYPRE_StructSolver solver,
int num_pre_relax)

*(Optional) Set number of pre-relaxation sweeps*

int
**HYPRE_StructPFMGSetNumPostRelax** (HYPRE_StructSolver solver,
int num_post_relax)

*(Optional) Set number of post-relaxation sweeps*

int
**HYPRE_StructPFMGSetSkipRelax** (HYPRE_StructSolver solver,
int skip_relax)

*(Optional) Skip relaxation on certain grids for isotropic problems*

int
**HYPRE_StructPFMGSetLogging** (HYPRE_StructSolver solver, int logging)

*(Optional) Set the amount of logging to do*

int
**HYPRE_StructPFMGSetPrintLevel** (HYPRE_StructSolver solver,
int print_level)

*(Optional) To allow printing to the screen*

int
**HYPRE_StructPFMGGetNumIterations** (HYPRE_StructSolver solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_StructPFMGGetFinalRelativeResidualNorm**
(HYPRE_StructSolver
solver,
double *norm)

*Return the norm of the final relative residual*

## Struct SMG Solver

**Names**

int
**HYPRE_StructSMGCreate** (MPI_Comm comm,
HYPRE_StructSolver *solver)
*Create a solver object*

int
**HYPRE_StructSMGDestroy** (HYPRE_StructSolver solver)
*Destroy a solver object*

int
**HYPRE_StructSMGSetup** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b, HYPRE_StructVector x)

int
**HYPRE_StructSMGSolve** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A, HYPRE_StructVector b,
HYPRE_StructVector x)
*Solve the system*

int
**HYPRE_StructSMGSetTol** (HYPRE_StructSolver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_StructSMGSetMaxIter** (HYPRE_StructSolver solver, int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_StructSMGSetRelChange** (HYPRE_StructSolver solver,
int rel_change)
*(Optional) Additionally require that the relative difference in successive iterates be small*

int
**HYPRE_StructSMGSetZeroGuess** (HYPRE_StructSolver solver)
*(Optional) Use a zero initial guess*

int
**HYPRE_StructSMGSetNonZeroGuess** (HYPRE_StructSolver solver)
*(Optional) Use a nonzero initial guess*

int
**HYPRE_StructSMGSetNumPreRelax** (HYPRE_StructSolver solver,
int num_pre_relax)
*(Optional) Set number of pre-relaxation sweeps*

int

**HYPRE_StructSMGSetNumPostRelax** (HYPRE_StructSolver solver,
int num_post_relax)

*(Optional) Set number of post-relaxation sweeps*

int
**HYPRE_StructSMGSetLogging** (HYPRE_StructSolver solver, int logging)

*(Optional) Set the amount of logging to do*

int
**HYPRE_StructSMGSetPrintLevel** (HYPRE_StructSolver solver,
int print_level)

*(Optional) To allow printing to the screen*

int
**HYPRE_StructSMGGetNumIterations** (HYPRE_StructSolver solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_StructSMGGetFinalRelativeResidualNorm** (HYPRE_StructSolver
solver,
double *norm)

*Return the norm of the final relative residual*

## 4.5 Struct PCG Solver

**Names**

int
**HYPRE_StructPCGCreate** (MPI_Comm comm,
HYPRE_StructSolver *solver)

*Create a solver object*

int
**HYPRE_StructPCGDestroy** (HYPRE_StructSolver solver)

*Destroy a solver object*

int
**HYPRE_StructPCGSetup** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b, HYPRE_StructVector x)

int
**HYPRE_StructPCGSolve** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A, HYPRE_StructVector b,
HYPRE_StructVector x)

*Solve the system*

int

**HYPRE_StructPCGSetTol** (HYPRE_StructSolver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_StructPCGSetMaxIter** (HYPRE_StructSolver solver, int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_StructPCGSetTwoNorm** (HYPRE_StructSolver solver,
int two_norm)
*(Optional) Use the two-norm in stopping criteria*

int
**HYPRE_StructPCGSetRelChange** (HYPRE_StructSolver solver,
int rel_change)
*(Optional) Additionally require that the relative difference in successive iterates be small*

int
**HYPRE_StructPCGSetPrecond** (HYPRE_StructSolver solver,
HYPRE_PtrToStructSolverFcn precond,
HYPRE_PtrToStructSolverFcn
precond_setup,
HYPRE_StructSolver precond_solver)
*(Optional) Set the preconditioner to use*

int
**HYPRE_StructPCGSetLogging** (HYPRE_StructSolver solver, int logging)
*(Optional) Set the amount of logging to do*

int
**HYPRE_StructPCGSetPrintLevel** (HYPRE_StructSolver solver, int level)
*(Optional) Set the print level*

int
**HYPRE_StructPCGGetNumIterations** (HYPRE_StructSolver solver,
int *num_iterations)
*Return the number of iterations taken*

int
**HYPRE_StructPCGGetFinalRelativeResidualNorm** (HYPRE_StructSolver
solver,
double *norm)
*Return the norm of the final relative residual*

int
**HYPRE_StructPCGGetResidual** (HYPRE_StructSolver solver,
void **residual)
*Return the residual*

int
**HYPRE_StructDiagScaleSetup** (HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector y,
HYPRE_StructVector x)
*Setup routine for diagonal preconditioning*

int

**HYPRE_StructDiagScale** (HYPRE_StructSolver solver,
HYPRE_StructMatrix HA,
HYPRE_StructVector Hy,
HYPRE_StructVector Hx)

*Solve routine for diagonal preconditioning*

**4.6**

## Struct GMRES Solver

**Names**

int
**HYPRE_StructGMRESCreate** ( MPI_Comm comm,
HYPRE_StructSolver *solver )

*Create a solver object*

int
**HYPRE_StructGMRESDestroy** ( HYPRE_StructSolver solver )

*Destroy a solver object*

int
**HYPRE_StructGMRESSetup** ( HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x )

*set up*

int
**HYPRE_StructGMRESSolve** ( HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x )

*Solve the system*

int
**HYPRE_StructGMRESSetTol** ( HYPRE_StructSolver solver, double tol )

*(Optional) Set the convergence tolerance*

int
**HYPRE_StructGMRESSetMaxIter** ( HYPRE_StructSolver solver,
int max_iter )

*(Optional) Set maximum number of iterations*

int
**HYPRE_StructGMRESSetPrecond** ( HYPRE_StructSolver solver,
HYPRE_PtrToStructSolverFcn precond,
HYPRE_PtrToStructSolverFcn
precond_setup,
HYPRE_StructSolver precond_solver )

*(Optional) Set the preconditioner to use*

int

**HYPRE_StructGMRESSetLogging** ( HYPRE_StructSolver solver,
int logging )

*(Optional) Set the amount of logging to do*

int
**HYPRE_StructGMRESSetPrintLevel** ( HYPRE_StructSolver solver,
int level )

*(Optional) Set the print level*

int
**HYPRE_StructGMRESGetNumIterations** ( HYPRE_StructSolver solver,
int *num_iterations )

*Return the number of iterations taken*

int
**HYPRE_StructGMRESGetFinalRelativeResidualNorm** (
HYPRE_StructSolver
solver,
double *norm )

*Return the norm of the final relative residual*

int
**HYPRE_StructGMRESGetResidual** ( HYPRE_StructSolver solver,
void **residual)

*Return the residual*

## 4.7 Struct BiCGSTAB Solver

**Names**

int
**HYPRE_StructBiCGSTABCreate** ( MPI_Comm comm,
HYPRE_StructSolver *solver )

*Create a solver object*

int
**HYPRE_StructBiCGSTABDestroy** ( HYPRE_StructSolver solver )

*Destroy a solver object*

int
**HYPRE_StructBiCGSTABSetup** ( HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x )

*set up*

int

**HYPRE_StructBiCGSTABSolve** ( HYPRE_StructSolver solver,
HYPRE_StructMatrix A,
HYPRE_StructVector b,
HYPRE_StructVector x )

*Solve the system*

int
**HYPRE_StructBiCGSTABSetTol** ( HYPRE_StructSolver solver, double tol )

*(Optional) Set the convergence tolerance*

int
**HYPRE_StructBiCGSTABSetMaxIter** ( HYPRE_StructSolver solver,
int max_iter )

*(Optional) Set maximum number of iterations*

int
**HYPRE_StructBiCGSTABSetPrecond** ( HYPRE_StructSolver solver,
HYPRE_PtrToStructSolverFcn
precond,
HYPRE_PtrToStructSolverFcn
precond_setup,
HYPRE_StructSolver precond_solver
)

*(Optional) Set the preconditioner to use*

int
**HYPRE_StructBiCGSTABSetLogging** ( HYPRE_StructSolver solver,
int logging )

*(Optional) Set the amount of logging to do*

int
**HYPRE_StructBiCGSTABSetPrintLevel** ( HYPRE_StructSolver solver,
int level )

*(Optional) Set the print level*

int
**HYPRE_StructBiCGSTABGetNumIterations** ( HYPRE_StructSolver
solver, int *num_iterations )

*Return the number of iterations taken*

int
**HYPRE_StructBiCGSTABGetFinalRelativeResidualNorm** (
HYPRE_StructSolver
solver,
double *norm
)

*Return the norm of the final relative residual*

int
**HYPRE_StructBiCGSTABGetResidual** ( HYPRE_StructSolver solver,
void **residual)

*Return the residual*

5

# extern SStruct Solvers

**Names**



These solvers use matrix/vector storage schemes that are taylored to semi-structured grid problems.

5.1

## SStruct Solvers

**Names**

typedef struct hypre_SStructSolver_struct* **HYPRE_SStructSolver**
*The solver object*

5.2

## SStruct PCG Solver

**Names**

int

**HYPRE_SStructPCGCreate** (MPI_Comm comm,
HYPRE_SStructSolver *solver)

*Create a solver object*

5.2.1 int
**HYPRE_SStructPCGDestroy** (HYPRE_SStructSolver solver)

*Destroy a solver object* ..... 50

int
**HYPRE_SStructPCGSetup** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

int
**HYPRE_SStructPCGSolve** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

*Solve the system*

int
**HYPRE_SStructPCGSetTol** (HYPRE_SStructSolver solver, double tol)

*(Optional) Set the convergence tolerance*

int
**HYPRE_SStructPCGSetMaxIter** (HYPRE_SStructSolver solver,
int max_iter)

*(Optional) Set maximum number of iterations*

int
**HYPRE_SStructPCGSetTwoNorm** ( HYPRE_SStructSolver solver,
int two_norm )

*(Optional) Set type of norm to use in stopping criteria*

int
**HYPRE_SStructPCGSetRelChange** ( HYPRE_SStructSolver solver,
int rel_change )

*(Optional) Set to use additional relative-change convergence test*

int
**HYPRE_SStructPCGSetPrecond** (HYPRE_SStructSolver solver,
HYPRE_PtrToSStructSolverFcn precond,
HYPRE_PtrToSStructSolverFcn
precond_setup, void *precond_solver)

*(Optional) Set the preconditioner to use*

int
**HYPRE_SStructPCGSetLogging** (HYPRE_SStructSolver solver, int logging)

*(Optional) Set the amount of logging to do*

int
**HYPRE_SStructPCGSetPrintLevel** (HYPRE_SStructSolver solver, int level)

*(Optional) Set the print level*

int

**HYPRE_SStructPCGGetNumIterations** (HYPRE_SStructSolver solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_SStructPCGGetFinalRelativeResidualNorm**
(HYPRE_SStructSolver
solver,
double *norm)

*Return the norm of the final relative residual*

int
**HYPRE_SStructPCGGetResidual** (HYPRE_SStructSolver solver,
void **residual)

*Return the residual*

**5.2.1**

int **HYPRE_SStructPCGDestroy** (HYPRE_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**5.3**

## SStruct BiCGSTAB Solver

**Names**

int
**HYPRE_SStructBiCGSTABCreate** (MPI_Comm comm,
HYPRE_SStructSolver *solver)

*Create a solver object*

5.3.1 int
**HYPRE_SStructBiCGSTABDestroy** (HYPRE_SStructSolver solver)

*Destroy a solver object* ..... 52

int

**HYPRE_SStructBiCGSTABSetup** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

int
**HYPRE_SStructBiCGSTABSolve** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

*Solve the system*

int
**HYPRE_SStructBiCGSTABSetTol** (HYPRE_SStructSolver solver,
double tol)

*(Optional) Set the convergence tolerance*

int
**HYPRE_SStructBiCGSTABSetMaxIter** (HYPRE_SStructSolver solver,
int max_iter)

*(Optional) Set maximum number of iterations*

int
**HYPRE_SStructBiCGSTABSetPrecond** (HYPRE_SStructSolver solver,
HYPRE_PtrToSStructSolverFcn
precond,
HYPRE_PtrToSStructSolverFcn
precond_setup,
void *precond_solver)

*(Optional) Set the preconditioner to use*

int
**HYPRE_SStructBiCGSTABSetLogging** (HYPRE_SStructSolver solver,
int logging)

*(Optional) Set the amount of logging to do*

int
**HYPRE_SStructBiCGSTABSetPrintLevel** (HYPRE_SStructSolver solver,
int level)

*(Optional) Set the print level*

int
**HYPRE_SStructBiCGSTABGetNumIterations** (HYPRE_SStructSolver
solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_SStructBiCGSTABGetFinalRelativeResidualNorm**
(HYPRE_SStructSolver
solver,
double
*norm)

*Return the norm of the final relative residual*

int

**HYPRE_SStructBiCGSTABGetResidual** (HYPRE_SStructSolver solver,
void **residual)

*Return the residual*

**5.3.1**

int **HYPRE_SStructBiCGSTABDestroy** (HYPRE_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**5.4**

## SStruct GMRES Solver

**Names**

int
**HYPRE_SStructGMRESCreate** (MPI_Comm comm,
HYPRE_SStructSolver *solver)

*Create a solver object*

5.4.1 int
**HYPRE_SStructGMRESDestroy** (HYPRE_SStructSolver solver)

*Destroy a solver object* ..... 53

int
**HYPRE_SStructGMRESSetup** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

int
**HYPRE_SStructGMRESSolve** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

*Solve the system*

int

**HYPRE_SStructGMRESSetKDim** (HYPRE_SStructSolver solver, int k_dim)
*(Optional) Set the maximum size of the Krylov space*

int
**HYPRE_SStructGMRESSetTol** (HYPRE_SStructSolver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_SStructGMRESSetMaxIter** (HYPRE_SStructSolver solver,
int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_SStructGMRESSetPrecond** (HYPRE_SStructSolver solver,
HYPRE_PtrToSStructSolverFcn
precond,
HYPRE_PtrToSStructSolverFcn
precond_setup, void *precond_solver)
*(Optional) Set the preconditioner to use*

int
**HYPRE_SStructGMRESSetLogging** (HYPRE_SStructSolver solver,
int logging)
*(Optional) Set the amount of logging to do*

int
**HYPRE_SStructGMRESSetPrintLevel** (HYPRE_SStructSolver solver,
int print_level)
*(Optional) Set the print level*

int
**HYPRE_SStructGMRESGetNumIterations** (HYPRE_SStructSolver solver,
int *num_iterations)
*Return the number of iterations taken*

int
**HYPRE_SStructGMRESGetFinalRelativeResidualNorm**
(HYPRE_SStructSolver
solver,
double *norm)
*Return the norm of the final relative residual*

int
**HYPRE_SStructGMRESGetResidual** (HYPRE_SStructSolver solver,
void **residual)
*Return the residual*

**5.4.1**

int **HYPRE_SStructGMRESDestroy** (HYPRE_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**5.5**

## SStruct SysPFMG Solver

**Names**

int
**HYPRE_SStructSysPFMGCreate** ( MPI_Comm comm,
HYPRE_SStructSolver *solver )
*Create a solver object*

int
**HYPRE_SStructSysPFMGDestroy** (HYPRE_SStructSolver solver)
*Destroy a solver object*

int
**HYPRE_SStructSysPFMGSetup** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)

int
**HYPRE_SStructSysPFMGSolve** (HYPRE_SStructSolver solver,
HYPRE_SStructMatrix A,
HYPRE_SStructVector b,
HYPRE_SStructVector x)
*Solve the system*

int
**HYPRE_SStructSysPFMGSetTol** (HYPRE_SStructSolver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_SStructSysPFMGSetMaxIter** (HYPRE_SStructSolver solver,
int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_SStructSysPFMGSetRelChange** (HYPRE_SStructSolver solver,
int rel_change)
*(Optional) Additionally require that the relative difference in successive iterates be small*

int
**HYPRE_SStructSysPFMGSetZeroGuess** (HYPRE_SStructSolver solver)
*(Optional) Use a zero initial guess*

int

**HYPRE_SStructSysPFMGSetNonZeroGuess** (HYPRE_SStructSolver solver)

*(Optional) Use a nonzero initial guess*

int
**HYPRE_SStructSysPFMGSetRelaxType** (HYPRE_SStructSolver solver, int relax_type)

*(Optional) Set relaxation type*

int
**HYPRE_SStructSysPFMGSetNumPreRelax** (HYPRE_SStructSolver solver, int num_pre_relax)

*(Optional) Set number of pre-relaxation sweeps*

int
**HYPRE_SStructSysPFMGSetNumPostRelax** (HYPRE_SStructSolver solver, int num_post_relax)

*(Optional) Set number of post-relaxation sweeps*

int
**HYPRE_SStructSysPFMGSetSkipRelax** (HYPRE_SStructSolver solver, int skip_relax)

*(Optional) Skip relaxation on certain grids for isotropic problems*

int
**HYPRE_SStructSysPFMGSetLogging** (HYPRE_SStructSolver solver, int logging)

*(Optional) Set the amount of logging to do*

int
**HYPRE_SStructSysPFMGSetPrintLevel** (HYPRE_SStructSolver solver, int print_level)

*(Optional) Set the print level*

int
**HYPRE_SStructSysPFMGGetNumIterations** (HYPRE_SStructSolver solver, int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_SStructSysPFMGGetFinalRelativeResidualNorm** ( HYPRE_SStructSolver solver, double *norm)

*Return the norm of the final relative residual*

6

# extern ParCSR Solvers

**Names**



These solvers use matrix/vector storage schemes that are taylored for general sparse matrix systems.

6.1

## ParCSR Solvers

**Names**

#define **HYPRE_SOLVER_STRUCT**
*The solver object*

6.2

## ParCSR BoomerAMG Solver and Preconditioner

int
**HYPRE_BoomerAMGCreate** (HYPRE_Solver *solver)
*Create a solver object*

int
**HYPRE_BoomerAMGDestroy** (HYPRE_Solver solver)
*Destroy a solver object*

6.2.1 int
**HYPRE_BoomerAMGSetup** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)
*Set up the BoomerAMG solver or preconditioner* ..... 59

6.2.2 int
**HYPRE_BoomerAMGSolve** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)
*Solve the system or apply AMG as a preconditioner* ..... 60

6.2.3 int
**HYPRE_BoomerAMGSolveT** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)
*Solve the transpose system $A^T x = b$ or apply AMG as a preconditioner to the transpose system* ..... 60

6.2.4 int
**HYPRE_BoomerAMGSetTol** (HYPRE_Solver solver, double tol)
*(Optional) Set the convergence tolerance, if BoomerAMG is used as a solver* ..... 61

6.2.5 int
**HYPRE_BoomerAMGSetMaxIter** (HYPRE_Solver solver, int max_iter)
*(Optional) Sets maximum number of iterations, if BoomerAMG is used as a solver* ..... 61

6.2.6 int
**HYPRE_BoomerAMGSetMaxLevels** (HYPRE_Solver solver, int max_levels)
*(Optional) Sets maximum number of multigrid levels* ..... 61

6.2.7 int
**HYPRE_BoomerAMGSetStrongThreshold** (HYPRE_Solver solver,
double strong_threshold)
*(Optional) Sets AMG strength threshold* ..... 61

6.2.8 int
**HYPRE_BoomerAMGSetMaxRowSum** (HYPRE_Solver solver,
double max_row_sum)
*(Optional) Sets a parameter to modify the definition of strength for diagonal dominant portions of the matrix* ..... 62

6.2.9 int
**HYPRE_BoomerAMGSetCoarsenType** (HYPRE_Solver solver,
int coarsen_type)
*(Optional) Defines which parallel coarsening algorithm is used* ..... 62

int

**HYPRE_BoomerAMGSetMeasureType** (HYPRE_Solver solver, int measure_type)

*(Optional) Defines whether local or global measures are used*

6.2.10 int

**HYPRE_BoomerAMGSetCycleType** (HYPRE_Solver solver, int cycle_type)

*(Optional) Defines the type of cycle* ..... 62

6.2.11 int

**HYPRE_BoomerAMGSetNumGridSweeps** (HYPRE_Solver solver, int *num_grid_sweeps)

*(Optional) Defines the number of sweeps for the fine and coarse grid, the up and down cycle* ..... 63

6.2.12 int

**HYPRE_BoomerAMGSetNumSweeps** (HYPRE_Solver solver, int num_sweeps)

*(Optional) Sets the number of sweeps* ..... 63

6.2.13 int

**HYPRE_BoomerAMGSetCycleNumSweeps** (HYPRE_Solver solver, int num_sweeps, int k)

*(Optional) Sets the number of sweeps at a specified cycle* ..... 63

6.2.14 int

**HYPRE_BoomerAMGSetGridRelaxType** (HYPRE_Solver solver, int *grid_relax_type)

*(Optional) Defines which smoother is used on the fine and coarse grid, the up and down cycle* ..... 64

6.2.15 int

**HYPRE_BoomerAMGSetRelaxType** (HYPRE_Solver solver, int relax_type)

*(Optional) Defines the smoother to be used* ..... 64

6.2.16 int

**HYPRE_BoomerAMGSetCycleRelaxType** (HYPRE_Solver solver, int relax_type, int k)

*(Optional) Defines the smoother at a given cycle* ..... 64

6.2.17 int

**HYPRE_BoomerAMGSetRelaxOrder** (HYPRE_Solver solver, int relax_order)

*(Optional) Defines in which order the points are relaxed* ..... 65

6.2.18 int

**HYPRE_BoomerAMGSetGridRelaxPoints** (HYPRE_Solver solver, int **grid_relax_points)

*(Optional) Defines in which order the points are relaxed* ..... 65

6.2.19 int

**HYPRE_BoomerAMGSetRelaxWeight** (HYPRE_Solver solver, double *relax_weight)

*(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR* ..... 65

6.2.20 int

Parallel unstructured algebraic multigrid solver and preconditioner

**6.2.1**

int
**HYPRE_BoomerAMGSetup** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Set up the BoomerAMG solver or preconditioner. If used as a preconditioner, this function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] object to be set up.
`A` — [IN] ParCSR matrix used to construct the solver/preconditioner.
`b` — Ignored by this function.
`x` — Ignored by this function.

**6.2.2**

int
**HYPRE_BoomerAMGSolve** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Solve the system or apply AMG as a preconditioner. If used as a preconditioner, this function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] solver or preconditioner object to be applied.
`A` — [IN] ParCSR matrix, matrix of the linear system to be solved
`b` — [IN] right hand side of the linear system to be solved
`x` — [OUT] approximated solution of the linear system to be solved

**6.2.3**

int
**HYPRE_BoomerAMGSolveT** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Solve the transpose system $A^T x = b$ or apply AMG as a preconditioner to the transpose system . If used as a preconditioner, this function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] solver or preconditioner object to be applied.
`A` — [IN] ParCSR matrix
`b` — [IN] right hand side of the linear system to be solved
`x` — [OUT] approximated solution of the linear system to be solved

**6.2.4**

int **HYPRE_BoomerAMGSetTol** (HYPRE_Solver solver, double tol)

(Optional) Set the convergence tolerance, if BoomerAMG is used as a solver. If it is used as a preconditioner, this function has no effect. The default is 1.e-7.

**6.2.5**

int **HYPRE_BoomerAMGSetMaxIter** (HYPRE_Solver solver, int max_iter)

(Optional) Sets maximum number of iterations, if BoomerAMG is used as a solver. If it is used as a preconditioner, this function has no effect. The default is 20.

**6.2.6**

int
**HYPRE_BoomerAMGSetMaxLevels** (HYPRE_Solver solver, int max_levels)

(Optional) Sets maximum number of multigrid levels. The default is 25.

**6.2.7**

int
**HYPRE_BoomerAMGSetStrongThreshold** (HYPRE_Solver solver, double strong_threshold)

(Optional) Sets AMG strength threshold. The default is 0.25. For 2d Laplace operators, 0.25 is a good value, for 3d Laplace operators, 0.5 or 0.6 is a better value. For elasticity problems, a large strength threshold, such as 0.9, is often better.

**6.2.8**

int
**HYPRE_BoomerAMGSetMaxRowSum** (HYPRE_Solver solver, double max_row_sum)

(Optional) Sets a parameter to modify the definition of strength for diagonal dominant portions of the matrix. The default is 0.9. If max_row_sum is 1, no checking for diagonally dominant rows is performed.

**6.2.9**

int
**HYPRE_BoomerAMGSetCoarsenType** (HYPRE_Solver solver, int coarsen_type)

(Optional) Defines which parallel coarsening algorithm is used. There are the following options for coarsen_type:

- 0 CLJP-coarsening (a parallel coarsening algorithm using independent sets.
- 1 classical Ruge-Stueben coarsening on each processor, no boundary treatment (not recommended!)
- 3 classical Ruge-Stueben coarsening on each processor, followed by a third pass, which adds coarse points on the boundaries
- 6 Falgout coarsening (uses 1 first, followed by CLJP using the interior coarse points generated by 1 as its first independent set)

The default is 6.

**6.2.10**

int
**HYPRE_BoomerAMGSetCycleType** (HYPRE_Solver solver, int cycle_type)

(Optional) Defines the type of cycle. For a V-cycle, set cycle_type to 1, for a W-cycle set cycle_type to 2. The default is 1.

**6.2.11**

int
**HYPRE_BoomerAMGSetNumGridSweeps** (HYPRE_Solver solver, int *num_grid_sweeps)

(Optional) Defines the number of sweeps for the fine and coarse grid, the up and down cycle.

Note: This routine will be phased out!!!! Use HYPRE_BoomerAMGSetNumSweeps or HYPRE_BoomerAMGSetCycleNumSweeps instead.

**6.2.12**

int
**HYPRE_BoomerAMGSetNumSweeps** (HYPRE_Solver solver, int num_sweeps)

(Optional) Sets the number of sweeps. On the finest level, the up and the down cycle the number of sweeps are set to num_sweeps and on the coarsest level to 1. The default is 1.

**6.2.13**

int
**HYPRE_BoomerAMGSetCycleNumSweeps** (HYPRE_Solver solver, int num_sweeps, int k)

(Optional) Sets the number of sweeps at a specified cycle. There are the following options for k:

| | |
|---|---|
| the finest level | if k=0 |
| the down cycle | if k=1 |
| the up cycle | if k=2 |
| the coarsest level | if k=3. |

**6.2.14**

int
**HYPRE_BoomerAMGSetGridRelaxType** (HYPRE_Solver solver, int *grid_relax_type)

(Optional) Defines which smoother is used on the fine and coarse grid, the up and down cycle.

Note: This routine will be phased out!!!! Use HYPRE_BoomerAMGSetRelaxType or HYPRE_BoomerAMGSetCycleRelaxType instead.

**6.2.15**

int
**HYPRE_BoomerAMGSetRelaxType** (HYPRE_Solver solver, int relax_type)

(Optional) Defines the smoother to be used. It uses the given smoother on the fine grid, the up and the down cycle and sets the solver on the coarsest level to Gaussian elimination (9). The default is Gauss-Seidel (3).

There are the following options for relax_type:

0 Jacobi
1 Gauss-Seidel, sequential (very slow!)
2 Gauss-Seidel, interior points in parallel, boundary sequential (slow!)
3 hybrid Gauss-Seidel or SOR, forward solve
4 hybrid Gauss-Seidel or SOR, backward solve
5 hybrid chaotic Gauss-Seidel (works only with OpenMP)
6 hybrid symmetric Gauss-Seidel or SSOR
9 Gaussian elimination (only on coarsest level)

**6.2.16**

int
**HYPRE_BoomerAMGSetCycleRelaxType** (HYPRE_Solver solver, int relax_type, int k)

(Optional) Defines the smoother at a given cycle. For options of relax_type see description of HYPRE_BoomerAMGSetRelaxType). Options for k are

| | |
|---|---|
| the finest level | if k=0 |
| the down cycle | if k=1 |
| the up cycle | if k=2 |
| the coarsest level | if k=3. |

**6.2.17**

int
**HYPRE_BoomerAMGSetRelaxOrder** (HYPRE_Solver solver, int relax_order)

(Optional) Defines in which order the points are relaxed. There are the following options for relax_order:

0 the points are relaxed in natural or lexicographic order on each processor
1 CF-relaxation is used, i.e on the fine grid and the down cycle the coarse points are relaxed first, followed by the fine points; on the up cycle the F-points are relaxed first, followed by the C-points. On the coarsest level, if an iterative scheme is used, the points are relaxed in lexicographic order.

The default is 1 (CF-relaxation).

**6.2.18**

int
**HYPRE_BoomerAMGSetGridRelaxPoints** (HYPRE_Solver solver, int **grid_relax_points)

(Optional) Defines in which order the points are relaxed.

Note: This routine will be phased out!!!! Use HYPRE_BoomerAMGSetRelaxOrder instead.

**6.2.19**

int
**HYPRE_BoomerAMGSetRelaxWeight** (HYPRE_Solver solver, double *relax_weight)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR.

Note: This routine will be phased out!!!! Use HYPRE_BoomerAMGSetRelaxWt or HYPRE_BoomerAMGSetLevelRelaxWt instead.

**6.2.20**

int
**HYPRE_BoomerAMGSetRelaxWt** (HYPRE_Solver solver, double relax_weight)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR on all levels.

| | |
|---|---|
| relax_weight > 0 | this assigns the given relaxation weight on all levels |
| relax_weight = 0 | the weight is determined on each level with the estimate $\frac{3}{4\|D^{-1/2}AD^{-1/2}\|}$, where $D$ is the diagonal matrix of $A$ (this should only be used with Jacobi) |
| relax_weight = -k | the relaxation weight is determined with at most k CG steps on each level (this should only be used for symmetric positive definite problems) |

The default is 1.

**6.2.21**

int
**HYPRE_BoomerAMGSetLevelRelaxWt** (HYPRE_Solver solver, double relax_weight, int level)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR on the user defined level. Note that the finest level is denoted 0, the next coarser level 1, etc. For nonpositive relax_weight, the parameter is determined on the given level as described for HYPRE_BoomerAMGSetRelaxWt. The default is 1.

**6.2.22**

int **HYPRE_BoomerAMGSetOmega** (HYPRE_Solver solver, double *omega)

(Optional) Defines the outer relaxation weight for hybrid SOR. Note: This routine will be phased out!!!! Use HYPRE_BoomerAMGSetOuterWt or HYPRE_BoomerAMGSetLevelOuterWt instead.

**6.2.23**

int **HYPRE_BoomerAMGSetOuterWt** (HYPRE_Solver solver, double omega)

(Optional) Defines the outer relaxation weight for hybrid SOR and SSOR on all levels.

| | |
|---|---|
| omega > 0 | this assigns the same outer relaxation weight omega on each level |
| omega = -k | an outer relaxation weight is determined with at most k CG steps on each level (this only makes sense for symmetric positive definite problems and smoothers, e.g. SSOR) |

The default is 1.

**6.2.24**

int **HYPRE_BoomerAMGSetLevelOuterWt** (HYPRE_Solver solver, double omega, int level)

(Optional) Defines the outer relaxation weight for hybrid SOR or SSOR on the user defined level. Note that the finest level is denoted 0, the next coarser level 1, etc. For nonpositive omega, the parameter is determined on the given level as described for HYPRE_BoomerAMGSetOuterWt. The default is 1.

**6.3**

## ParCSR ParaSails Preconditioner

**Names**

int
**HYPRE_ParaSailsCreate** (MPI_Comm comm, HYPRE_Solver *solver)
*Create a ParaSails preconditioner*

int
**HYPRE_ParaSailsDestroy** (HYPRE_Solver solver)
*Destroy a ParaSails preconditioner*

6.3.1 int
**HYPRE_ParaSailsSetup** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)
*Set up the ParaSails preconditioner* ..... 69

6.3.2 int
**HYPRE_ParaSailsSolve** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)
*Apply the ParaSails preconditioner* ..... 69

6.3.3 int
**HYPRE_ParaSailsSetParams** (HYPRE_Solver solver, double thresh, int nlevels)
*Set the threshold and levels parameter for the ParaSails preconditioner* ... 69

6.3.4 int
**HYPRE_ParaSailsSetFilter** (HYPRE_Solver solver, double filter)
*Set the filter parameter for the ParaSails preconditioner* ..... 70

6.3.5 int
**HYPRE_ParaSailsSetSym** (HYPRE_Solver solver, int sym)
*Set the symmetry parameter for the ParaSails preconditioner* ..... 70

6.3.6 int
**HYPRE_ParaSailsSetLoadbal** (HYPRE_Solver solver, double loadbal)
*Set the load balance parameter for the ParaSails preconditioner* ..... 71

6.3.7 int
**HYPRE_ParaSailsSetReuse** (HYPRE_Solver solver, int reuse)
*Set the pattern reuse parameter for the ParaSails preconditioner* ..... 71

6.3.8 int
**HYPRE_ParaSailsSetLogging** (HYPRE_Solver solver, int logging)
*Set the logging parameter for the ParaSails preconditioner* ..... 71

6.3.9 int
**HYPRE_ParaSailsBuildIJMatrix** (HYPRE_Solver solver, HYPRE_IJMatrix *pij_A)
*Build IJ Matrix of the sparse approximate inverse (factor)* ..... 72

Parallel sparse approximate inverse preconditioner for the ParCSR matrix format.

**6.3.1**

int
**HYPRE_ParaSailsSetup** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Set up the ParaSails preconditioner. This function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] Preconditioner object to set up.
`A` — [IN] ParCSR matrix used to construct the preconditioner.
`b` — Ignored by this function.
`x` — Ignored by this function.

**6.3.2**

int
**HYPRE_ParaSailsSolve** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Apply the ParaSails preconditioner. This function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] Preconditioner object to apply.
`A` — Ignored by this function.
`b` — [IN] Vector to precondition.
`x` — [OUT] Preconditioned vector.

**6.3.3**

int
**HYPRE_ParaSailsSetParams** (HYPRE_Solver solver, double thresh, int nlevels)

Set the threshold and levels parameter for the ParaSails preconditioner. The accuracy and cost of ParaSails are parameterized by these two parameters. Lower values of the threshold parameter and higher values of levels parameter lead to more accurate, but more expensive preconditioners.

**Parameters:**

`solver` — [IN] Preconditioner object for which to set parameters.
`thresh` — [IN] Value of threshold parameter, $0 \leq$ thresh $\leq 1$. The default value is 0.1.
`nlevels` — [IN] Value of levels parameter, $0 \leq$ nlevels. The default value is 1.

### 6.3.4

int **HYPRE_ParaSailsSetFilter** (HYPRE_Solver solver, double filter)

Set the filter parameter for the ParaSails preconditioner.

**Parameters:**

`solver` — [IN] Preconditioner object for which to set filter parameter.
`filter` — [IN] Value of filter parameter. The filter parameter is used to drop small nonzeros in the preconditioner, to reduce the cost of applying the preconditioner. Values from 0.05 to 0.1 are recommended. The default value is 0.1.

### 6.3.5

int **HYPRE_ParaSailsSetSym** (HYPRE_Solver solver, int sym)

Set the symmetry parameter for the ParaSails preconditioner.

**Parameters:**

`solver` — [IN] Preconditioner object for which to set symmetry parameter.
`sym` — [IN] Value of the symmetry parameter:

| value | meaning |
|---|---|
| 0 | nonsymmetric and/or indefinite problem, and nonsymmetric preconditioner |
| 1 | SPD problem, and SPD (factored) preconditioner |
| 2 | nonsymmetric, definite problem, and SPD (factored) preconditioner |

**6.3.6**

int **HYPRE_ParaSailsSetLoadbal** (HYPRE_Solver solver, double loadbal)

Set the load balance parameter for the ParaSails preconditioner.

**Parameters:**

`solver` — [IN] Preconditioner object for which to set the load balance parameter.
`loadbal` — [IN] Value of the load balance parameter, $0 \leq$ loadbal $\leq 1$. A zero value indicates that no load balance is attempted; a value of unity indicates that perfect load balance will be attempted. The recommended value is 0.9 to balance the overhead of data exchanges for load balancing. No load balancing is needed if the preconditioner is very sparse and fast to construct. The default value when this parameter is not set is 0.

**6.3.7**

int **HYPRE_ParaSailsSetReuse** (HYPRE_Solver solver, int reuse)

Set the pattern reuse parameter for the ParaSails preconditioner.

**Parameters:**

`solver` — [IN] Preconditioner object for which to set the pattern reuse parameter.
`reuse` — [IN] Value of the pattern reuse parameter. A nonzero value indicates that the pattern of the preconditioner should be reused for subsequent constructions of the preconditioner. A zero value indicates that the preconditioner should be constructed from scratch. The default value when this parameter is not set is 0.

**6.3.8**

int **HYPRE_ParaSailsSetLogging** (HYPRE_Solver solver, int logging)

Set the logging parameter for the ParaSails preconditioner.

**Parameters:** `solver` — [IN] Preconditioner object for which to set the logging parameter. `logging` — [IN] Value of the logging parameter. A nonzero value sends statistics of the setup procedure to stdout. The default value when this parameter is not set is 0.

**6.3.9**

int
**HYPRE_ParaSailsBuildIJMatrix** (HYPRE_Solver solver, HYPRE_IJMatrix *pij_A)

Build IJ Matrix of the sparse approximate inverse (factor). This function explicitly creates the IJ Matrix corresponding to the sparse approximate inverse or the inverse factor. Example: HYPRE_IJMatrix ij_A; HYPRE_ParaSailsBuildIJMatrix(solver, &ij_A);

**Parameters:** `solver` — [IN] Preconditioner object.
`pij_A` — [OUT] Pointer to the IJ Matrix.

**6.4**

## ParCSR Euclid Preconditioner

**Names**

int
**HYPRE_EuclidCreate** (MPI_Comm comm, HYPRE_Solver *solver)
*Create a Euclid object*

int
**HYPRE_EuclidDestroy** (HYPRE_Solver solver)
*Destroy a Euclid object*

MPI Parallel ILU preconditioner

Options summary:

| Option | Default | Synopsis |
|---|---|---|
| -level | 1 | ILU($k$) factorization level |
| -bj | 0 (false) | Use Block Jacobi ILU instead of PILU |
| -eu_stats | 0 (false) | Print internal timing and statistics |
| -eu_mem | 0 (false) | Print internal memory usage |

**6.4.1**

int
**HYPRE_EuclidSetup** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Set up the Euclid preconditioner. This function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] Preconditioner object to set up.
`A` — [IN] ParCSR matrix used to construct the preconditioner.
`b` — Ignored by this function.
`x` — Ignored by this function.

**6.4.2**

int
**HYPRE_EuclidSolve** (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)

Apply the Euclid preconditioner. This function should be passed to the iterative solver `SetPrecond` function.

**Parameters:**
`solver` — [IN] Preconditioner object to apply.
`A` — Ignored by this function.
`b` — [IN] Vector to precondition.
`x` — [OUT] Preconditioned vector.

**6.4.3**

int **HYPRE_EuclidSetParams** (HYPRE_Solver solver, int argc, char *argv[])

Insert (name, value) pairs in Euclid's options database by passing Euclid the command line (or an array of strings). All Euclid options (e.g, level, drop-tolerance) are stored in this database. If a (name, value) pair already exists, this call updates the value. See also: HYPRE_EuclidSetParamsFromFile.

**Parameters:**
`argc` — [IN] Length of argv array
`argv` — [IN] Array of strings

**6.4.4**

int
**HYPRE_EuclidSetParamsFromFile** (HYPRE_Solver solver, char *filename)

Insert (name, value) pairs in Euclid's options database. Each line of the file should either begin with a "#," indicating a comment line, or contain a (name value) pair, e.g:

```
>cat optionsFile
#sample runtime parameter file
-blockJacobi 3
-matFile /home/hysom/myfile.euclid
-doSomething true
-xx_coeff -1.0
```

See also: HYPRE_EuclidSetParams.

**Parameters:** `filename[IN]` — Pathname/filename to read

**6.5**

## ParCSR Pilut Preconditioner

**Names**

int
**HYPRE_ParCSRPilutCreate** (MPI_Comm comm, HYPRE_Solver *solver)
*Create a preconditioner object*

int
**HYPRE_ParCSRPilutDestroy** (HYPRE_Solver solver)
*Destroy a preconditioner object*

int
**HYPRE_ParCSRPilutSetup** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)

int
**HYPRE_ParCSRPilutSolve** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)
*Precondition the system*

int
**HYPRE_ParCSRPilutSetMaxIter** (HYPRE_Solver solver, int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_ParCSRPilutSetDropTolerance** (HYPRE_Solver solver, double tol)
*(Optional)*

int
**HYPRE_ParCSRPilutSetFactorRowSize** (HYPRE_Solver solver, int size)
*(Optional)*

**6.6**

## ParCSR PCG Solver

**Names**

int

**HYPRE_ParCSRPCGCreate** (MPI_Comm comm, HYPRE_Solver *solver)
*Create a solver object*

int
**HYPRE_ParCSRPCGDestroy** (HYPRE_Solver solver)
*Destroy a solver object*

int
**HYPRE_ParCSRPCGSetup** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)

int
**HYPRE_ParCSRPCGSolve** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)
*Solve the system*

int
**HYPRE_ParCSRPCGSetTol** (HYPRE_Solver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_ParCSRPCGSetMaxIter** (HYPRE_Solver solver, int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_ParCSRPCGSetTwoNorm** (HYPRE_Solver solver, int two_norm)
*(Optional) Use the two-norm in stopping criteria*

int
**HYPRE_ParCSRPCGSetRelChange** (HYPRE_Solver solver, int rel_change)
*(Optional) Additionally require that the relative difference in successive iterates be small*

int
**HYPRE_ParCSRPCGSetPrecond** (HYPRE_Solver solver,
HYPRE_PtrToParSolverFcn precond,
HYPRE_PtrToParSolverFcn
precond_setup,
HYPRE_Solver precond_solver)
*(Optional) Set the preconditioner to use*

int
**HYPRE_ParCSRPCGGetPrecond** (HYPRE_Solver solver,
HYPRE_Solver *precond_data)

int
**HYPRE_ParCSRPCGSetLogging** (HYPRE_Solver solver, int logging)
*(Optional) Set the amount of logging to do*

int
**HYPRE_ParCSRPCGSetPrintLevel** (HYPRE_Solver solver, int print_level)
*(Optional) Set the print level*

int

**HYPRE_ParCSRPCGGetNumIterations** (HYPRE_Solver solver,
int *num_iterations)

*Return the number of iterations taken*

int
**HYPRE_ParCSRPCGGetFinalRelativeResidualNorm** (HYPRE_Solver
solver,
double *norm)

*Return the norm of the final relative residual*

int
**HYPRE_ParCSRDiagScaleSetup** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector y,
HYPRE_ParVector x)

*Setup routine for diagonal preconditioning*

int
**HYPRE_ParCSRDiagScale** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix HA,
HYPRE_ParVector Hy, HYPRE_ParVector Hx)

*Solve routine for diagonal preconditioning*

## 6.7 ParCSR GMRES Solver

**Names**

int
**HYPRE_ParCSRGMRESCreate** (MPI_Comm comm,
HYPRE_Solver *solver)

*Create a solver object*

int
**HYPRE_ParCSRGMRESDestroy** (HYPRE_Solver solver)

*Destroy a solver object*

int
**HYPRE_ParCSRGMRESSetup** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b,
HYPRE_ParVector x)

int
**HYPRE_ParCSRGMRESSolve** (HYPRE_Solver solver,
HYPRE_ParCSRMatrix A,
HYPRE_ParVector b, HYPRE_ParVector x)

*Solve the system*

int

**HYPRE_ParCSRGMRESSetKDim** (HYPRE_Solver solver, int k_dim)
*(Optional) Set the maximum size of the Krylov space*

int
**HYPRE_ParCSRGMRESSetTol** (HYPRE_Solver solver, double tol)
*(Optional) Set the convergence tolerance*

int
**HYPRE_ParCSRGMRESSetMaxIter** (HYPRE_Solver solver, int max_iter)
*(Optional) Set maximum number of iterations*

int
**HYPRE_ParCSRGMRESSetPrecond** (HYPRE_Solver solver,
HYPRE_PtrToParSolverFcn precond,
HYPRE_PtrToParSolverFcn
precond_setup,
HYPRE_Solver precond_solver)
*(Optional) Set the preconditioner to use*

int
**HYPRE_ParCSRGMRESGetPrecond** (HYPRE_Solver solver,
HYPRE_Solver *precond_data)

int
**HYPRE_ParCSRGMRESSetLogging** (HYPRE_Solver solver, int logging)
*(Optional) Set the amount of logging to do*

int
**HYPRE_ParCSRGMRESSetPrintLevel** (HYPRE_Solver solver,
int print_level)
*(Optional) Set print level*

int
**HYPRE_ParCSRGMRESGetNumIterations** (HYPRE_Solver solver,
int *num_iterations)
*Return the number of iterations taken*

int
**HYPRE_ParCSRGMRESGetFinalRelativeResidualNorm** (HYPRE_Solver
solver,
double *norm)
*Return the norm of the final relative residual*

# Class Graph